

Note

The cat and the noisy mouse

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ABSTRACT

We consider a variant of a pursuit and evasion game studied independently by Britnell and Wildon as well as Haslegrave. In their game, a cat has to catch an invisible mouse that moves along the edges of some graph G . In our version, the cat receives partial information about its distance to the mouse, and we show that the cat has a winning strategy if and only if G is a forest. Seager proposed a similar game with complete distance information whose rules cause some small yet important differences to the game we consider.

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1. Introduction

We consider a variant of a pursuit and evasion game independently studied by Britnell and Wildon [2], Komarov and Winkler [6], and Haslegrave [4]. The game is played by two players, called the *cat* and the *mouse* in [4], on a finite graph G known to both, and proceeds in discrete rounds numbered by positive integers. In round i , the cat chooses a vertex c_i of G and also the mouse chooses a vertex m_i of G . While the choice of the cat is unrestricted among all vertices of G , the mouse must move along an edge of G , more precisely, the vertices m_i and m_{i+1} have to be distinct yet adjacent for every i . The cat catches the mouse, and thereby wins the game, in round i as soon as $c_i = m_i$. The mouse wins the game if it can avoid being caught indefinitely, more precisely, the mouse wins if for every positive integer k , and every sequence c_1, \dots, c_k of vertices of G , there is a sequence m_1, \dots, m_k of vertices of G such that m_{i+1} is a neighbor of m_i for every $i \in [k-1]$, and $c_i \neq m_i$ for every $i \in [k]$. As shown by Britnell and Wildon [2], Komarov and Winkler [6], and Haslegrave [4], the cat has a winning strategy in their game played on G if and only if G is a forest that does not contain the tree T^* shown in Fig. 1.

The key feature of their game is the invisibility of the mouse, that is, the cat does not know the position of the mouse until it actually catches it. In the variant that we consider here, the cat receives some information about the distance $\text{dist}_G(c_i, m_i)$ in G between c_i and m_i in every round i ; what information exactly is specified at the beginning of the next section. Figuratively, the cat estimates its current distance to the mouse using the noise made by the mouse's movement.

Seager [7] introduced a similar game, where the cat, called *cop*, knows its exact distance to the mouse, called *robber*, yet the objective of the cat is to determine the exact position of the mouse at least once. This weaker objective makes the game easier for the cat; knowing where a robber is at some point in time is easier than catching him. There are further differences in Seager's game. The mouse is forbidden to move to the previous position of the cat but it is allowed not to move at all, that is, m_{i+1} is an element of $(\{m_i\} \cup N_G(m_i)) \setminus \{c_i\}$. Allowing $m_{i+1} = m_i$ but not requiring $m_{i+1} \neq c_i$ within Haslegrave's game, leads to a trivial situation where any distance information is useless, because the mouse can avoid capture indefinitely as soon as the graph has at least one edge. Also, requiring $m_{i+1} \in N_G(m_i) \setminus \{c_i\}$ within Haslegrave's game, changes the game considerably; if this modified game is played on T^* , and the cat plays $(c_1, \dots, c_7) = (x, v_1, x, v_2, x, v_3, x)$, then, at some point, the mouse is either caught or has no legal move. In fact, since every second vertex played by the cat is x , in order to avoid capture, the mouse must stay in $\{u_j, v_j, w_j\}$ for some $j \in [3]$. Now, when the cat plays $c_i = v_j$, the mouse m_i is in $\{u_j, w_j\}$.

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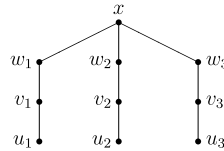


Fig. 1. The tree T^* .

Furthermore, if the mouse m_i is at w_j , then it will be caught on x in the next round, and if it is at u_j , then it has no legal move to play. It is unknown what happens to Haslegrave’s game if both conditions are imposed, that is, $m_{i+1} \in (\{m_i\} \cup N_C(m_i)) \setminus \{c_i\}$. Altogether, Seager’s game shows some small yet important differences to the game that we consider here. For improved bounds, better strategies, and variants of Seager’s game refer to [1,5,8].

As shown in [3,7], the cop wins Seager’s game on many graphs that contain cycles, while, in our game, the mouse wins as soon as there is any cycle C . In fact, the mouse’s strategy is to stay on C throughout the game, and, since every vertex of C has two neighbors on C , the cat will never be able to guarantee catching the mouse; if the cat chooses a neighbor c_{i+1} of m_i , then m_{i+1} can be chosen to be the neighbor of m_i on C that is distinct from c_{i+1} .

Our main result is that the cat has a winning strategy on G exactly if G is a forest.

2. Result

We consider Haslegrave’s game with partial distance information for the cat. In what follows, let d_i denote the distance $\text{dist}_C(c_i, m_i)$ for every positive integer i . In the original game, the cat learns in every round i , whether d_i is “0” or “at least 1”. In the version that we consider, the cat receives the following information in every round i :

- whether d_i is “0” or “1” or “at least 2”, and, additionally,
- for $i \geq 2$, whether d_i is “at most d_{i-1} ” or “bigger than d_{i-1} ”.

In order to show that the cat has a winning strategy on forests, it suffices to describe a winning strategy on trees; the cat can apply this strategy to the different components of any forest, one by one, and will eventually catch the mouse. As we see below, the maximum number of rounds that the mouse can evade capture when the cat plays our strategy on a tree is bounded in terms of the order of the tree. Therefore, if the cat plays on some component of a forest, and this number of rounds is reached without capture, then the mouse must be in another component.

Let T be a tree. The cat chooses an arbitrary vertex r of T as its *root*. For every vertex u of T , let V_u denote the set of vertices that contains u and all its descendants.

We consider the game as a sequence of *transitions* from some round i to some later round $i + j$. In order to show that the cat has a winning strategy, we argue that until it catches the mouse, it can ensure that all these transitions are of one of four different simple types, which allows the cat to make progress. See Fig. 2 for an illustration.

The situation at the beginning of a transition starting with round i is characterized by

- a *reference vertex* r_i , and
- two sets X_i and Y_i of vertices.

The set X_i contains all vertices that are not a descendant of r_i , which includes r_i itself, as well as all vertices in sets V_u for some children u of r_i . Let the children of r_i that do not belong to X_i be the leaves v_1, \dots, v_k and the non-leaves w_1, \dots, w_ℓ . The set Y_i is the possibly empty union of sets V_u for some children u of w_1 . Let the children of w_1 that do not belong to Y_i be the vertices x_1, \dots, x_p . Note that k, ℓ , and p are all non-negative integers that might be 0, and that the cat is free to choose the ordering of the mentioned vertices.

In the round i starting the current transition, the cat chooses c_i equal to the reference vertex r_i . Furthermore, exploiting knowledge acquired in earlier rounds, the cat is sure that m_i does not lie in $X_i \cup Y_i$. For $i = 1$, that is, in the very first round, the reference vertex r_1 is the root r of T , X_1 contains only r_1 , and Y_1 is empty. Note that either $c_1 = r_1 = m_1$, in which case the cat wins right away, or $m_1 \notin X_1 \cup Y_1$.

As said above, we consider four types of transitions from some round i to some later round $i + j$ that are characterized by the following conditions.

- **Type 1**
 $d_i = 1, j = 1, r_{i+1}$ equals r_i, X_{i+1} equals $X_i, Y_{i+1} = \emptyset$, and $d_{i+1} \geq 2$.
- **Type 2**
 $d_i \geq 2, j = 1, r_{i+1}$ is a child of r_i, X_i is a proper subset of X_{i+1} , and $Y_{i+1} = \emptyset$.
- **Type 3**
 $d_i \geq 2, j \in \{1, 2\}, r_{i+j}$ equals r_i, X_i is a proper subset of X_{i+j} , and $Y_{i+j} = \emptyset$.

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