# On the determinant of the Laplacian matrix of a complex unit gain graph ${ }^{\text {¹ }}$ 

Yi Wang ${ }^{\text {a,* }}$, Shi-Cai Gong ${ }^{\text {b }}$, Yi-Zheng Fan ${ }^{\text {a }}$<br>a School of Mathematical Sciences, Anhui University, Hefei, Anhui, 230601, PR China<br>b School of Science, Zhejiang University of Science and Technology, Hangzhou, Zhejiang, 310023, PR China

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#### Abstract

Let $G$ be a complex unit gain graph which is obtained from an undirected graph $\Gamma$ by assigning a complex unit $\varphi\left(v_{i} v_{j}\right)$ to each oriented edge $v_{i} v_{j}$ such that $\varphi\left(v_{i} v_{j}\right) \varphi\left(v_{j} v_{i}\right)=1$ for all edges. The Laplacian matrix of $G$ is defined as $L(G)=D(G)-A(G)$, where $D(G)$ is the degree diagonal matrix of $\Gamma$ and $A(G)=\left(a_{i j}\right)$ has $a_{i j}=\varphi\left(v_{i} v_{j}\right)$ if $v_{i}$ is adjacent to $v_{j}$ and $a_{i j}=0$ otherwise. In this paper, we provide a combinatorial description of $\operatorname{det}(L(G))$ that generalizes that for the determinant of the Laplacian matrix of a signed graph.


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## 1. Introduction

In the past few decades, researchers have extensively studied the adjacency, Laplacian, normalized Laplacian and signless Laplacian matrices of an undirected graph. Then there has been a growing study of matrices associated to a signed graph $[9,14-17,30]$ and to an oriented graph [1,21]. Recently, researchers investigated matrices associated to a more general graph - a complex unit gain graph [20].

Let $\mathbb{T}$ be the circle group which is the multiplicative group of all complex numbers with absolute value 1 . A $\mathbb{T}$-gain graph is arised from a simple graph with an orientation such that each orientation of an edge is given a complex unit of $\mathbb{T}$, called a gain, and the inverse of this complex unit assigned to the opposite orientation of such an edge. A $\mathbb{T}$-gain graph is also referred as a complex unit gain graph; see [20]. Let $\Gamma=(V, E)$ be the underlying graph of a $\mathbb{T}$-gain graph with vertex set $V=\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$ and edge set $E \vec{E}=\vec{E}(\Gamma)$ is defined to be the set of oriented edges of such a gain graph. For a $\mathbb{T}$-gain graph, denote by $e_{i j}$ the oriented edge from $v_{i}$ to $v_{j}$ and by $\varphi\left(e_{i j}\right)$ the gain of $e_{i j}$. Hence a $\mathbb{T}$-gain graph is a triple $G=(\Gamma, \mathbb{T}, \varphi)$ consisting of an underlying graph $\Gamma=(V, E)$, the circle group $\mathbb{T}$ and a function $\varphi: \vec{E}(\Gamma) \rightarrow \mathbb{T}$ (called the gain function), such that $\varphi\left(e_{i j}\right)=\varphi\left(e_{j i}\right)^{-1}$; see [20]. For simplicity, we sometimes write $G=(\Gamma, \varphi)$ for a $\mathbb{T}$-gain graph. For more properties of $\mathbb{T}$-gain graphs, one can see for example [3,12,23-29]. Note that the definition of a weighted directed graph by Bapat et al. [5] is same as a $\mathbb{T}$-gain graph.

Let $G=(\Gamma, \varphi)$ be a $\mathbb{T}$-gain graph with vertex set $\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$. The adjacency matrix $A(G)=\left(a_{i j}\right)_{n \times n}$ of $G$ is defined by

$$
a_{i j}= \begin{cases}\varphi\left(e_{i j}\right), & \text { if } v_{i} \text { is adjacent to } v_{j} \\ 0, & \text { otherwise }\end{cases}
$$

[^0]One can see that if $v_{i}$ is adjacent to $v_{j}$, then $a_{i j}=\varphi\left(e_{i j}\right)=\left(\varphi\left(e_{j i}\right)\right)^{-1}=\bar{a}_{j i}$, the conjugate of $a_{j i}$. Denote by $D(G)=$ $\operatorname{diag}\left\{d\left(v_{1}\right), d\left(v_{2}\right), \ldots, d\left(v_{2}\right)\right\}$ the degree diagonal matrix of the underlying graph $\Gamma$. The Laplacian matrix $L(G)=\left(l_{i j}\right)_{n \times n}$ of $G$ is defined as $L(G)=D(G)-A(G)$. Therefore, both of $A(G)$ and $L(G)$ are Hermitian.

Let $G$ be a $\mathbb{T}$-gain graph with Laplacian matrix $L(G)$. Bapat et al. [5] and Reff [20] independently point out that the definition of $L(G)$ coincides with the Laplacian matrix of the underlying graph of $\Gamma$ if $G$ has gain $1 ; L(G)$ coincides with the signless Laplacian matrix of $\Gamma$ if $G$ has gain -1 ; and $L(G)$ coincides with the Laplacian matrix of a signed graph (a signed graph is also named by Bapat et al. as a mixed graph; see for example $[4,5])$ if $G$ has gains $\{1,-1\}$.

The graph obtained from a simple undirected graph by assigning an orientation to each of its edges is named as the oriented graph, denoted by $\vec{G}$. The skew adjacency matrix $A(\vec{G})=\left(a_{i j}\right)$ related to an oriented graph $\vec{G}$ is defined as $a_{i j}=-a_{j i}=1$ if there exists an edge with tail $v_{i}$ and head $v_{j}$; and $a_{i j}=0$ otherwise. The skew Laplacian matrix of $\vec{G}$ is defined as $L(\vec{G})=D(\vec{G})-A(\vec{G})$; see [2], where $D(\vec{G})$ denotes the degree diagonal matrix of $\vec{G}$. Unlike the adjacency matrix and the Laplacian matrix of an undirected graph, there has been little research on the skew-adjacency matrix $A(\vec{G})$ and the skew Laplacian matrix $L(\vec{G})$ of an oriented graph $\vec{G}$, except that in enumeration of perfect matchings of a graph, see [18] and references therein, where the square of the number of perfect matchings of a graph $\vec{G}$ with a Pfaffian orientation is the determinant of the skew-adjacency matrix $A(\vec{G})$. Recently, researchers investigated the spectral properties of matrices associated to an oriented graph; see [1,2,7,10,11,18,19,21,22]. By the definition of the adjacency matrix of a $\mathbb{T}$-gain graph, we can see that the adjacency matrix $A=\left(a_{i j}\right)_{n \times n}$ of a graph $\mathbb{T}$ with gain set $\{\mathbf{i},-\mathbf{i}\}$ can be considered the skew adjacency matrix of an oriented graph multiplied by the complex number $\mathbf{i}$, that is, $a_{i j}=-a_{j i}=\mathbf{i}$ if there exists an edge from $v_{i}$ to $v_{j}$; and $a_{i j}=0$ otherwise. Therefore, the Laplacian matrix of the graph $\mathbb{T}$ with gain set $\{\mathbf{i},-\mathbf{i}\}$ can be viewed as another version of the Laplacian matrix of oriented graphs, that is, $L(\vec{G})=D(\vec{G})-\mathbf{i} A(\vec{G})$.

Therefore, most classical graph matrices, including Laplacian, normalized Laplacian, signless Laplacian matrices of a graph, and the Laplacian matrix of an oriented graph can be viewed as a special case of the Laplacian matrix of a $\mathbb{T}$-gain graph.

The classical Matrix Tree Theorem in its simplest form [6, pp.219] gives a combinatorial characterization of a minor of the Laplacian matrix of a graph in terms of spanning trees of the underlying graph. Then the Matrix Tree Theorem for signed graphs is given by Zaslavsky [23, Theorem 8A.4] and a combinatorial proof of the all minors matrix tree theorem is given by Chaiken [8]. In this paper, we provide a combinatorial description the determinant of the Laplacian matrix of an arbitrary $\mathbb{T}$-gain graph, which is a generalization for the determinant of the Laplacian matrix of a signed graph.

## 2. The determinant of a complex unit gain graph

Throughout this paper, all $\mathbb{T}$-gain graphs have simple underlying graphs, i.e., without loops and multi-edges, $\bar{a}$ denotes the conjugate of the complex number $a$ and $A^{*}$ denotes the Hermitian transpose of the complex matrix $A$. Given a $\mathbb{T}$-gain graph $G$, a maximal connected subgraph of $G$ is called a component of $G$. For convenience, in terms of defining subgraph and degree of a $\mathbb{T}$-gain graph, we focus only on its underlying graph. Certainly, each subgraph of a gain graph is also referred as a gain graph and preserves the gain of each edge, even if we do not state it specifically.

We first need to introduce the notion of the vertex-edge incidence matrix of a $\mathbb{T}$-gain graph, which was introduced in [29] for more general gain graphs. Let $G=(\Gamma, \varphi)$ be a $\mathbb{T}$-gain graph with vertex set $\Gamma(V)=\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$ and edge set $\Gamma(\vec{E})=\left\{e_{1}, e_{2}, \ldots, e_{m}\right\}$. Then the vertex-edge incidence matrix $M(G)=\left(m_{i j}\right)_{n \times m}$ of $G$ is defined by

$$
m_{v_{i} e}= \begin{cases}1, & \text { if } e=e_{i j} \in \vec{E} \text { for some vertex } v_{j} \\ -\varphi\left(e_{j i}\right), & \text { if } e=e_{j i} \in \vec{E} \text { for some vertex } v_{j} \\ 0, & \text { otherwise }\end{cases}
$$

This definition can be considered as a particular incidence matrix related to a $\mathbb{T}$-gain graph defined by Reff [20]. From Lemma 3.1 in $[20] L(G)=M(G) M(G)^{*}$, then $L(G)$ is positive semi-definite and has a nonnegative determinant.

A connected $\mathbb{T}$-gain graph containing no cycles is called a $\mathbb{T}$-gain tree [20]. Since a $\mathbb{T}$-gain tree of order $n$ contains exactly $n-1$ edges, its vertex-edge incidence matrix is an $n \times(n-1)$ Hermitian matrix. We begin with the following result, which is a consequence of Corollary 3.4 in [20] or of Theorem 2.1 in [27].

Lemma 2.1. Let $T$ be an arbitrary $\mathbb{T}$-gain tree with Laplacian matrix $L(T)$. Then

$$
\operatorname{det}(L(T))=0
$$

Let $C=v_{1} e_{1,2} v_{2} \cdots v_{s-1} e_{s-1, s} v_{s}\left(=v_{1}\right)$ be a cycle with $s(\geq 3)$ edges, where $v_{j}$ adjacent to $v_{j+1}$ for $j=1,2 \cdots, s-1$ and $v_{1}$ incident to $v_{s}$. The gain of $C$, denoted by $\varphi(C)$, is defined as

$$
\varphi(C)=\varphi\left(e_{1,2}\right) \varphi\left(e_{2,3}\right) \cdots \varphi\left(e_{s-1, s}\right) \varphi\left(e_{s, 1}\right)
$$

By the definition of the Laplacian matrix of a $\mathbb{T}$-gain graph, we have $l_{i, j}=-\varphi\left(e_{i, j}\right)$ whenever $v_{i}$ adjacent to $v_{j}$, then $\varphi(C)$ can be defined in terms of the entries of its Laplacian matrix as

$$
\varphi(C)=(-1)^{s} l_{1,2} l_{2,3} \cdots l_{s-1, s} l_{s, 1}
$$

The following result shows that the determinant of the Laplacian matrix of a $\mathbb{T}$-gain cycle is determined by its gain.

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    * Corresponding author.

    E-mail addresses: wangy@ahu.edu.cn (Y. Wang), scgong@zust.edu.cn (S.-C. Gong), fanyz@ahu.edu.cn (Y.-Z. Fan).

