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Oscillation criteria for a class of third order damped differential equations

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Abstract. The present study concerns the oscillation of a class of third-order nonlinear delay differential equations with middle term. We offer a new description of oscillation of the third-order equations in terms of oscillation of a related well studied second-order linear differential equation without damping. By using the integral averaging technique, we establish new oscillation results for this equation. Some examples are provided to illustrate the main results.

Keywords: Oscillation; Third-order; Functional delay; Differential equations

2010 Mathematics Subject Classification: 34K10; 34K11

1. INTRODUCTION

This paper is concerned with the oscillation and the asymptotic behavior of the third-order nonlinear functional differential equations with delayed argument

$$\left(r_{2}\left(\tau\right)\left(r_{1}\left(\tau\right)\left(y'\left(\tau\right)\right)^{\alpha}\right)'\right)' + \phi\left(\tau, y'\left(\delta\left(\tau\right)\right)\right) + q\left(\tau\right) f\left(y\left(\sigma\left(\tau\right)\right)\right) = 0,$$
(1.1)

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for $\tau \geq \tau_0$. Assume that the following conditions are satisfied:

- (C₁) $r_1, r_2, q \in C(I, \mathbb{R}^+), \delta, \sigma \in C(I, \mathbb{R})$ such that $I = [\tau_0, \infty), \delta(\tau) \le \tau, \sigma(\tau) \le \tau$, $\sigma'(\tau) > 0$ and $\lim_{\tau \to \infty} \delta(\tau) = \lim_{\tau \to \infty} \sigma(\tau) = \infty$.
- (C₂) There is a real function p(t), p(t) > 0 such that $\phi(\tau, u) \ge k_1 p(\tau) u^{\alpha}$ and $\phi(\tau, -u) = -\phi(\tau, u)$.
- (C₃) $f \in C(\mathbb{R}, \mathbb{R})$ such that $f(x)/x^{\beta} \ge k_2 > 0$, where α and β are quotients of odd positive integers.

A function y is called a solution of (1.1), if $y(\tau)$ satisfies (1.1) and if $y, r_1(y')^{\alpha}$ and $r_2(r_1(y')^{\alpha})' \in C^1([\tau_y, \infty), \mathbb{R})$ for some $\tau_y \geq \tau_0$. We only consider those solutions of (1.1) which satisfy $\sup\{|y(\tau)|: \tau_1 \leq \tau < \infty\} > 0$ for any $\tau_1 \in I$ and exist on *I*. Such a solution is called oscillatory if it has arbitrarily large zeros, otherwise it is called nonoscillatory.

Determining oscillation and nonoscillation of functional differential equations received deal of a great interest in recent years, see the papers [1-24]. Special cases of Eq. (1.1) include the equation

$$\left(r_{2}(\tau)\left(r_{1}(\tau)y'(\tau)\right)'\right)' + p(\tau)y'(\tau) + q(\tau)f(y(g(\tau))) = 0.$$
(1.2)

The oscillatory behavior of solutions of (1.2) has been discussed in a number of studies, see for example the papers by Tiryaki et al. [23], Aktas et al. [3], Grace [17] and Padhi et al. [20].

In this paper, we study the oscillation and asymptotic behavior of solutions of Eq. (1.1). Our results improve and unify the results in Tiryaki et al. [23] and Elabbasy et al. [11], and to extend and generalize the earlier ones presented in Bohner et al. [7].

2. Some Lemmas

In this section, we state and prove the following lemmas which we will use in the proof of our main results. For simplicity, we introduce the following notation:

$$E_{0}y = y, \ E_{1}y = r_{1}((E_{0}y)')^{a}, \ E_{2}y = r_{2}(E_{1}y)', \ E_{3} = (E_{2}y)',$$
$$R_{1}(\tau, \tau_{1}) = \int_{\tau_{1}}^{\tau} \frac{ds}{(r_{1}(s))^{\frac{1}{\alpha}}}, \ R_{2}(\tau, \tau_{1}) = \int_{\tau_{1}}^{\tau} \frac{ds}{r_{2}(s)},$$

and

$$R_{12}(\tau,\tau_1) = \int_{\tau_1}^{\tau} \left(\frac{R_2(s,\tau_1)}{r_1(s)}\right)^{\frac{1}{\alpha}} ds,$$

for $\tau_0 \leq \tau_1 \leq \tau < \infty$. We suppose that

 $R_1(\tau, \tau_0) \to \infty$ as $\tau \to \infty$

and

 $R_2(\tau, \tau_0) \to \infty \text{ as } \tau \to \infty.$

Lemma 2.1. [*Grace* [17]] *Assume that* $x(\tau)$ *is a bounded solution of equation*

$$\left(r_2\left(\tau\right)x'\left(\tau\right)\right)' = G\left(\tau\right)x\left(h\left(\tau\right)\right). \tag{2.1}$$

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