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Fast and Reliable Computation of Generalized Synthetic Controls

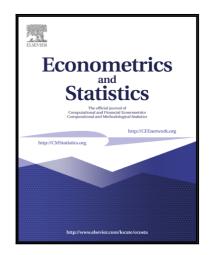
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Highlights

- Theory on methods for fast and reliably computing synthetic controls is provided.
- Existing implementations are shown to be unreliable in real-world applications.
- A reliable and free open source implementation is available, the R package MSCMT.



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