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The inverse mean problem of geometric and contraharmonic means

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Abstract

In this paper we solve the inverse mean problem of contraharmonic and geometric means of positive definite matrices (proposed in [W.N. Anderson, M.E. Mays, T.D. Morley, G.E. Trapp, The contraharmonic mean of HSD matrices, SIAM J. Algebra Disc. Meth. 8 (1987) 674–682])

$$\begin{cases} A = X + Y - 2(X^{-1} + Y^{-1})^{-1} \\ B = X \# Y, \end{cases}$$

by proving its equivalence to the well-known nonlinear matrix equation $X = T - BX^{-1}B$ where $T = \frac{1}{2}(A + A\#(A + 8BA^{-1}B))$ is the unique positive definite solution of $X = A + 2BX^{-1}B$. The inverse mean problem is solvable if and only if $B \leq A$. © 2005 Elsevier Inc. All rights reserved.

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1. Introduction

In [2] Anderson and coauthors have introduced a natural matrix generalization of the contraharmonic mean of scalars $(a^2 + b^2)/(a + b)$ and studied related fixed point and least squares problems on positive semidefinite matrices. The contraharmonic mean C(A, B) of positive definite matrices A and B is defined by

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$$C(A, B) = A + B - 2(A^{-1} + B^{-1})^{-1}.$$

Inverse mean problems involving the contraharmonic mean are considered and answered for the problem of contraharmonic and arithmetric means in [2] where the inverse mean problem of contraharmonic and geometric means is proposed even for the scalar version. The geometric mean A#B of positive definite matrices A and B is defined by $A#B = A^{1/2}(A^{-1/2}BA^{-1/2})^{1/2}A^{1/2}$ and is well-known in theory of matrix inequalities (cf. [4–6]) and appears in semidefinite programming (scaling point, [20]) and in geometry (geodesic middle, [16,8,18]). Although the inverse mean problem occurs on positive semidefinite matrices A and B, we restrict our attention to the positive definite case. Similar questions on geometric, arithmetic and harmonic means are answered in [3].

The inverse mean problem of contraharmonic and geometric means is to find positive definite matrices X and Y for the system of nonlinear matrix equations:

$$\begin{cases} A = C(X, Y), \\ B = X \# Y, \end{cases}$$
(1.1)

where A and B are given positive definite matrices of same size. The main result of this paper is that the inverse mean problem (1.1) is equivalent to a system of the well-known nonlinear matrix equations (Theorem 2.3):

$$\begin{cases} X = A + 2BX^{-1}B, \\ Y = X - BY^{-1}B. \end{cases}$$
(1.2)

The matrix equations $X = Q + A^*X^{-1}A$ and $X = Q - A^*X^{-1}A$ with Q positive definite have been studied recently by several authors (see [1,9,10]). For the application areas where the equations arise, see the references given in [1,12].

In Section 3, we compute an explicit solution T of the first equation

$$X = A + 2BX^{-1}B$$

of (1.2) and then assert that the inverse mean problem is equivalent to the matrix equation

$$X = T - BX^{-1}B.$$

Solving directly the matrix equation $X = T - BX^{-1}B$ we conclude that the inverse mean problem is solvable if and only if $2B \le T$, equivalently $B \le A$ (Theorem 3.3). Extreme solutions of the inverse mean problem are also discussed.

2. The inverse mean problem

The following characterization and properties of the geometric mean are well-known. See [4,5,13,18,7] for multivariable geometric means.

Lemma 2.1 (The Riccati Lemma). *The geometric mean A#B of positive definite matrices A and B is the unique positive definite solution of the Riccati equation*

$$XA^{-1}X = B.$$

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