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All solutions of system of ill-posed operator equations of the first kind

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Abstract

In this paper, we discuss the structure of the solution space of system of operator equations of the first kind $A_i u = f_i$, i = 1, 2, ..., n in Hilbert spaces. If it has solutions, we give the analytic representation of all its solutions. Final examples show our methods are effective.

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1. Introduction

Let H, H_1 be separable Hilbert spaces, and let $A:H \to H_1$ be a bounded linear operator. Consider operator equations of the first kind

$$Au = f, \quad u \in H, \quad f \in H_1. \tag{1}$$

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Usually, operator equations of the first kind is ill-posed, so the problem of how to solve Eq. (1) becomes very important. Here, ill-posed means that at least one of the following three conditions cannot be satisfied:

- (1) Eq. (1) has solutions for every $f \in H_1$;
- (2) Eq. (1) has a unique solution for every $f \in H_1$;
- (3) inverse operator A^{-1} is continuous.

Usually, in order to solve Eq. (1), it needs to suppose that A^{-1} is single-valued. In this paper, Only supposing ill-posed Eq. (1) has solutions, we discuss the structure of its solution space and obtained the following results:

- (1) If Eq. (1) has solutions, we represent its solution space as $u_0 + N(A)$, where u_0 is the minimal norm solution of Eq. (1), and N(A) is the null space of operator A, namely, $N(A) = \{x \in H | Ax = 0\}$;
- (2) a complete orthonormal system of N(A) is given.

For generality, we directly discuss the following system of linear operator Eqs. (I) in Hilbert spaces,

$$\begin{cases} A_{1}u = f_{1} \\ A_{2}u = f_{2} \\ \vdots \\ A_{n}u = f_{n} \end{cases} u \in H, \ f_{i} \in H_{1}, \ i = 1, 2, \dots, n,$$

$$\vdots$$

$$(I)$$

where H, H_1 are separable Hilbert spaces, for every i = 1, 2, ..., n, $A_i: H \to H_1$ is a bounded linear operator.

2. Lemmas

Throughout this paper, we suppose that $A_i: H \to H_1$ is a bound linear operator, $N(A_i)$ is the null space of operator A_i , namely, $N(A_i) = \{x \in H | A_i x = 0\}$. For $M \subset H_1$, we denote $span\ M$ by [M] and the closure of M by \overline{M} . Suppose $\{r_i\}_{i=1}^{\infty} \subset H$, and we use $\{\bar{r}_i\}_{i=1}^{\infty}$ to denote the system of functions that is obtained from $\{r_i\}_{i=1}^{\infty}$ by Gram–Schmidt process of orthonormalization.

We can easily obtain the following lemma.

Lemma 2.1. Suppose $\{0\} \neq \{r_i\}_{i=1}^{\infty}, \{v_i\}_{i=1}^{\infty} \subset H$. Define $\{\bar{r}_i\}_{i=1}^{\infty}$ and $\{\tilde{v}_i\}_{i=1}^{\infty}$ as follows:

$$\bar{r}_1 = \frac{r_1}{\|r_1\|},\tag{2}$$

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