

Available online at www.sciencedirect.com



ADVANCES IN Mathematics

Advances in Mathematics 192 (2005) 135-182

http://www.elsevier.com/locate/aim

U(1)-invariant special Lagrangian 3-folds. III. Properties of singular solutions

Dominic Joyce

Lincoln College, Oxford University, Oxford OX1 3DR, UK

Received 7 June 2002; accepted 30 March 2004

Communicated by Gang Tian

Abstract

This is the last of three papers studying special Lagrangian 3-submanifolds (SLV 3-folds) N in \mathbb{C}^3 invariant under the U(1)-action $e^{i\theta}:(z_1, z_2, z_3) \mapsto (e^{i\theta}z_1, e^{i\theta}z_2, z_3)$, using analytic methods. If N is such a 3-fold then $|z_1|^2 - |z_2|^2 = 2a$ on N for some $a \in \mathbb{R}$. Locally, N can be written as a kind of graph of functions $u, v : \mathbb{R}^2 \to \mathbb{R}$ satisfying a nonlinear Cauchy–Riemann equation depending on a, so that u + iv is like a holomorphic function of x + iy.

The first paper studied the case *a* nonzero, and proved existence and uniqueness for solutions of two *Dirichlet problems* derived from the nonlinear Cauchy–Riemann equation. This yields existence and uniqueness of a large class of *nonsingular* U(1)-invariant SL 3-folds in \mathbb{C}^3 , with boundary conditions. The second paper extended these results to *weak solutions* of the Dirichlet problems when a = 0, giving existence and uniqueness of many *singular* U(1)-invariant SL 3-folds in \mathbb{C}^3 , with boundary conditions.

This third paper studies the *singularities* of these SL 3-folds. We show that under mild conditions the singularities are *isolated*, and have a *multiplicity* n > 0, and one of two *types*. Examples are constructed with every multiplicity and type. We also prove the existence of large families of U(1)-invariant *special Lagrangian fibrations* of open sets in \mathbb{C}^3 , including singular fibres.

© 2004 Elsevier Inc. All rights reserved.

MSC: 53C38; 53D12

Keywords: Special Lagrangian submanifold; Singularity; Nonlinear Cauchy–Riemann equation; Dirichlet problem

E-mail address: dominic.joyce@lincoln.ox.ac.uk.

^{0001-8708/\$ -} see front matter \odot 2004 Elsevier Inc. All rights reserved. doi:10.1016/j.aim.2004.03.016

1. Introduction

Special Lagrangian submanifolds (SL *m*-folds) are a distinguished class of real *m*-dimensional minimal submanifolds in \mathbb{C}^m , which are calibrated with respect to the *m*-form Re $(dz_1 \wedge \cdots \wedge dz_m)$. They can also be defined in Calabi–Yau manifolds, are important in String Theory, and are expected to play a rôle in the eventual explanation of Mirror Symmetry between Calabi–Yau 3-folds.

This is the third in a suite of three papers [9,10] studying special Lagrangian 3-folds N in \mathbb{C}^3 invariant under the U(1)-action

$$\mathbf{e}^{i\theta}: (z_1, z_2, z_3) \mapsto (\mathbf{e}^{i\theta} z_1, \mathbf{e}^{-i\theta} z_2, z_3) \quad \text{for } \mathbf{e}^{i\theta} \in \mathbf{U}(1).$$
(1)

These three papers and [11] are reviewed in [12]. Locally, we can write N as

$$N = \left\{ (z_1, z_2, z_3) \in \mathbb{C}^3 : \operatorname{Im}(z_3) = u(\operatorname{Re}(z_3), \operatorname{Im}(z_1 z_2)), \\ \operatorname{Re}(z_1 z_2) = v(\operatorname{Re}(z_3), \operatorname{Im}(z_1 z_2)), \quad |z_1|^2 - |z_2|^2 = 2a \right\},$$
(2)

where $a \in \mathbb{R}$ and $u, v : \mathbb{R}^2 \to \mathbb{R}$ are continuous functions. It was shown in [9] that when $a \neq 0$, N is an SL 3-fold in \mathbb{C}^3 if and only if u, v satisfy

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$$
 and $\frac{\partial v}{\partial x} = -2(v^2 + y^2 + a^2)^{1/2}\frac{\partial u}{\partial y}$, (3)

and then u, v are smooth and N is nonsingular.

Here is what we mean by saying N is locally of the form (2). Every connected U(1)invariant SL 3-fold N may be written in the form (2) for u, v continuous, multi-valued 'functions' (multifunctions). Since (3) is a nonlinear Cauchy–Riemann equation, u + ivis a bit like a holomorphic function of x + iy, and so the multifunctions (u, v) behave like holomorphic multifunctions in complex analysis, such as \sqrt{z} .

Thus we expect them to have isolated *branch points* in \mathbb{R}^2 . Over simply connected open sets $U \subset \mathbb{R}^2$ not containing any branch points, the multifunctions (u, v) decompose into *sheets*, each of which is a continuous, single-valued function. This is like choosing a branch of \sqrt{z} on a simply connected open subset $U \subset \mathbb{C} \setminus \{0\}$. In terms of N, we expect there to be a discrete set of 'branch point' U(1)-orbits, and small U(1)-invariant open sets in N away from these can be written in the form (2) for single-valued (u, v).

As $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ there exists $f : \mathbb{R}^2 \to \mathbb{R}$ with $\frac{\partial f}{\partial y} = u$ and $\frac{\partial f}{\partial x} = v$, satisfying

$$\left(\left(\frac{\partial f}{\partial x}\right)^2 + y^2 + a^2\right)^{-1/2} \frac{\partial^2 f}{\partial x^2} + 2\frac{\partial^2 f}{\partial y^2} = 0.$$
 (4)

In [9, Theorem 7.6] we proved existence and uniqueness for the Dirichlet problem for (4) in strictly convex domains S in \mathbb{R}^2 when $a \neq 0$. This gives existence and uniqueness of a large class of nonsingular U(1)-invariant SL 3-folds in \mathbb{C}^3 satisfying certain boundary conditions.

136

Download English Version:

https://daneshyari.com/en/article/9518129

Download Persian Version:

https://daneshyari.com/article/9518129

Daneshyari.com