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Totally Positive Bases and Progressive Iteration Approximation

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Abstract—In this paper, we study the progressive iteration approximation property of a curve (tensor product surface) generated by blending a given data point set and a set of basis functions The curve (tensor product surface) has the progressive iteration approximation property as long as the basis is totally positive and the corresponding collocation matrix is nonsingular. Thus, the Bspline and NURBS curve (surface) have the progressive iteration approximation property, and Bézier curve (surface) also has the property of the corresponding collocation matrix is nonsingular. © 2005 Elsevier Ltd. All rights reserved.

Keywords—Progressive iteration approximation, Total positivity, NURBS, B-spline, Bézier.

1. INTRODUCTION

Given a sequence of points $\{\mathbf{P}_i\}_{i=0}^n$, the *i*th point of which is assigned a parameter value t_i , $i = 0, 1, \ldots, n$, and a nonnegative basis $\{B_i(t) \ge 0 \mid t \in \mathbb{R}, i = 0, 1, \ldots, n\}$ with $\sum_{i=0}^n B_i(t) = 1$, the initial curve can be generated as follows, i.e., $\mathbf{C}^0(t) = \sum_{i=0}^n \mathbf{P}_i^0 B_i(t)$, with $\{\mathbf{P}_i^0 = \mathbf{P}_i\}_{i=0}^n$. By calculating the adjusting vector for each control point $\mathbf{\Delta}_i^0 = \mathbf{P}_i - \mathbf{C}^0(t_i), i = 0, 1, \ldots, n$, and letting $\{\mathbf{P}_i^1 = \mathbf{P}_i^0 + \mathbf{\Delta}_i^0\}_{i=0}^n$, we can get the next curve $\mathbf{C}^1(t) = \sum_{i=0}^n \mathbf{P}_i^1 B_i(t), \ldots$, and so on. Thus, at last, we get a sequence of curves $\{\mathbf{C}^{k}(t) \mid k = 0, 1, ...\}$ (see Figure 1).

Qi and de Boor have shown that, if the given nonnegative basis is a uniform cubic B-spline basis, and the parameter value t_i assigned to each data point happens to be at the knot of the knot vector on which the uniform cubic B-spline basis is defined, the curve sequence converges to a curve interpolating the given point sequence, i.e., $\lim_{k\to\infty} \mathbf{C}^k(t_i) = \mathbf{P}_i^0$, i = 0, 1, ..., n [1,2]. We say that the initial curve has the progressive iteration approximation property.

Furthermore, in [3], the authors have shown that not only the nonuniform cubic B-spline curve, but the nonuniform cubic B-spline tensor product surface also has the progressive iteration approximation property.

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Figure 1 Progressive iteration approximation, from $\mathbf{C}^{k}(t)$ to $\mathbf{C}^{k+1}(t)$.

In this paper, we will show that, as long as the given basis is totally positive, and its corresponding collocation matrix is nonsingular, the curve and tensor product surface generated by the basis have the *progressive iteration approximation* property. So, the B-spline, and NURBS curve and surface all have the *progressive iteration approximation* property, and Bézier curves and surfaces also have the *progressive iteration approximation* property, if the corresponding collocation matrix is nonsingular

The layout of this paper is as follows. In Section 2, we establish the *progressive iteration* approximation property of the curve and tensor product surface generated by a totally positive blending basis with nonsingular collocation matrix. In Section 3, we point out that the NURBS curve and surface have the *progressive iteration approximation* property. In Section 4, some results illustrating the *progressive iteration approximation* property of the Bézier (B-spline, NURBS) curve (surface) are given, and the fitting errors are also listed. At last, we conclude the paper in Section 5.

2. PROGRESSIVE ITERATION APPROXIMATION OF CURVES AND SURFACES

A nonnegative basis $\{B_i \ge 0 \mid i = 0, 1, ..., n\}$ with $\sum_{i=0}^n B_i = 1$ is called a *blending basis*. Based on the blending basis and a given data point set $\{\mathbf{P}_i \in \mathbf{R}^3\}_{i=0}^n$ $(\{\mathbf{P}_{ij} \in \mathbf{R}^3\}_{i=0,j=0}^m)$, we can generate a blending curve,

$$\mathbf{C}\left(t\right) = \sum_{i=0}^{n} \mathbf{P}_{i} B_{i}\left(t\right),\tag{2.1}$$

or a tensor product blending surface,

$$\mathbf{S}(u,v) = \sum_{i=0}^{m} \sum_{j=0}^{n} \mathbf{P}_{ij} B_i(u) B_j(v), \qquad (2.2)$$

where \mathbf{P}_i and \mathbf{P}_{ij} are called *control points*.

In the following, we first present the definition of a totally positive basis.

DEFINITION 2 1. Given a basis $\{B_i(t) \ge 0 \mid i = 0, 1, ..., n\}$ defined on $\Xi \subseteq \mathbb{R}$ and an increasing sequence $\tau_0 < \tau_1 < \cdots < \tau_m$ in Ξ , the collocation matrix of B_0, \ldots, B_n at $\tau_0 < \tau_1 < \cdots < \tau_m$ is the matrix,

$$M\begin{pmatrix} B_0, \dots, B_n\\ \tau_0, \dots, \tau_m \end{pmatrix} := (B_j(\tau_i))_{i=0,\dots,m,\,j=0,\dots,n}$$
(2.3)

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