



Asymptotic theory for bent-cable regression—the basic case[☆]

Grace Chiu^{a,b,*}, Richard Lockhart^a, Richard Routledge^a

^a*Department of Statistics and Actuarial Science, Simon Fraser University, Burnaby, British Columbia, Canada V5A 1S6*

^b*Pacific Institute for the Mathematical Sciences, Simon Fraser University, Burnaby, British Columbia, Canada V5A 1S6*

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Abstract

We use what we call the bent-cable model to describe potential change-point phenomena. The class of bent cables includes the commonly used broken stick (a bent cable without a bend segment). Theory for least-squares (LS) estimation is developed for the basic bent cable, whose incoming and outgoing linear phases have slopes 0 and 1, respectively, and are joined smoothly by a quadratic bend. Conditions on the design are given to ensure regularity of the estimation problem, despite non-differentiability of the model's first partial derivatives (with respect to the covariate and model parameters). Under such conditions, we show that the LS estimators (i) are consistent, regardless of a zero or positive true bend width; and (ii) asymptotically follow a bivariate normal distribution, if the underlying cable has all three segments. In the latter case, we show that the deviance statistic has an asymptotic chi-squared distribution with two degrees of freedom.

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* Corresponding author.

E-mail addresses: sgchiu@stat.sfu.ca, grace@pims.math.ca (G. Chiu), lockhart@stat.sfu.ca (R. Lockhart), routledg@stat.sfu.ca (R. Routledge).

1. Introduction

Given known design points x_1, \dots, x_n , we consider random responses Y_1, \dots, Y_n generated by the regression model

$$Y_i = q(x_i; \tau_0, \gamma_0) + \varepsilon_i, \quad i = 1, \dots, n, \quad (1)$$

where

$$q(x; \tau, \gamma) = \frac{(x - \tau + \gamma)^2}{4\gamma} \mathbf{1}\{|x - \tau| \leq \gamma\} + (x - \tau) \mathbf{1}\{x - \tau > \gamma\} \quad (2)$$

is referred to as the *basic bent cable* (Fig. 1), and ε_i 's are i.i.d. random errors with mean 0 and known, constant standard deviation σ .¹ We write $\boldsymbol{\theta}_0 = (\tau_0, \gamma_0)$.

Least-squares (LS) estimation of $\boldsymbol{\theta}_0 \in \Omega = (-\infty, M] \times [0, \infty)$ on the open regression domain $\mathcal{X} = \mathbb{R}$ is considered. Here, M is some finite positive upper bound (large) for the candidate τ -values. Zero is the natural lower bound for candidate γ -values. Any basic bent cable $q(x; \boldsymbol{\theta})$ for $\boldsymbol{\theta} \in \Omega$ is a candidate model. In this article, we prove, given a set of conditions on the location of the design points x_1, \dots, x_n (Section 3), that the least-squares estimators (LSEs) for τ_0 and γ_0 are consistent when $\gamma_0 \geq 0$, and asymptotically follow a bivariate normal distribution when $\gamma_0 > 0$. Asymptotic distributional properties for the case of $\gamma_0 = 0$ appear in Chiu et al. (2002a). A bent cable with free slope parameters is required in practice. The full bent-cable model can be written as $f(x; \beta_0, \beta_1, \beta_2, \tau, \gamma) = \beta_0 + \beta_1 x + \beta_2 q(x; \tau, \gamma)$. This article is intended to provide a framework for the complex estimation theory associated with the full model.

Seber and Wild (1989, Chapter 9) have suggested employing the class of bent-cable models—which includes the piecewise-linear “broken-stick” model when $\gamma = 0$ —in situations where both smooth and sharp transitions are plausible. However, modeling change phenomena by the broken stick remains common (Barrowman and Myers, 2000; Naylor and Su, 1998; Neuman et al., 2001). Numerical instability due to the non-differentiability of this model prompted Tishler and Zang (1981) to develop (2). Their introduction of a “phoney” bend of fixed, non-trivial width γ to replace the kink at τ was a computational tactic. Upon numerical convergence, γ would be ignored.

However, when no law of nature or auxiliary knowledge is available to support an abruptness notion, a broken-stick fit would encourage the investigator to look for sources of change associated with the sole value of $\hat{\tau}$. In contrast, the bent cable incorporates γ as part of the parametric model. It generalizes the broken stick by removing the a priori assumption of a sharp threshold, allowing for a possibly gradual transition. A bent-cable fit would point to one or more sources of change whose influence took hold gradually over a certain covariate range. Thus, it helps to avoid data misinterpretation due to possible over-simplification of the nature of change. We call it the “bent cable” due to the smooth bend as opposed to a sharp break in a snapped stick. The performance of bent-cable regression for assessing the abruptness of change is discussed in Chiu et al. (2002b).

¹ In practice, estimation of σ may be required. Chiu (2002) shows that the results of this article extend to LS estimation assuming unknown σ , and that the LSE of σ is consistent.

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