Model 3G

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### Improved on-line estimation for gamma process

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#### HIGHLIGHTS

- Two new recursive estimators are developed for homogeneous gamma process.
- We show that the two estimators are weakly consistent.
- We compare the two new estimators with these of Paroissin (2017) by simulations.

#### ARTICLE INFO

Article history: Received 24 January 2018 Received in revised form 27 April 2018 Accepted 25 July 2018 Available online xxxx ABSTRACT

In this paper, two new estimators based on the spirit of the best linear unbiased estimators are separately developed for homogeneous gamma process. Both estimators can be computed recursively, and have high efficiency. We compare the two new estimators with these of Paroissin (2017) by simulations, and find that ours have smaller biases and mean squared errors.

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### 1. Introduction

On-line inference has become an indispensable technique in prognostic and health management (Si et al., 2011; Guan et al., 2016; Wang et al., 2018; Xu et al., 2018; Zhou and Xu, 2018). Most of the on-line inference methods are developed based on the Wiener process. However, the Wiener process is suitable only for degradation processes that is not monotone. For the monotone degradation process, the gamma process is more effective and has received wide applications (Lawless and Crowder, 2004; Ye et al., 2014; Guida et al., 2015; Le Son et al., 2016). Recently, Paroissin (2017) considered on-line estimation of the following homogeneous gamma degradation process { $X(t), t \ge 0$ }:

1. X(0) = 0.

- 2. X(t) has independent increments.
- 3. The increment  $X(t + \Delta t) X(t)$  follows the gamma distribution with shape parameter  $a\Delta t$  and rate parameter b.

Consider *n* identical items whose degradation of a performance characteristic follows the above homogeneous gamma process, and let  $0 = t_0 < t_1 < t_2 < \cdots < t_m < \cdots$  be the measurement time epoches identical for all items, and  $X_i(t_j)$  be the degradation value of the *i*th item at time  $t_j$ . Let  $Y_{i,j} = X_i(t_j) - X_i(t_{j-1})$  and  $s_j = t_j - t_{j-1}$ ,  $j = 1, \ldots, m$ ,  $i = 1, \ldots, n$ .

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Then  $Y_{i,i}$  follows the gamma distribution with shape parameter  $as_i$  and rate parameter b. Following the notation in Paroissin (2017), let  $\tilde{Y}_{i,j} = Y_{i,j}/s_j$ ,  $\bar{Y}_{.j} = \frac{1}{n} \sum_{i=1}^n \tilde{Y}_{i,j}$  and  $\tau_j^2 = \frac{s_j}{n-1} \sum_{i=1}^n \left(\tilde{Y}_{i,j} - \bar{Y}_{.j}\right)^2$ . Then  $E(\bar{Y}_{.j}) = a/b \doteq \mu$  and  $E(\tau_j^2) = a/b^2 \doteq \sigma^2$ . Paroissin (2017) proposed two estimators for  $\mu$  and  $\sigma^2$ , which can be computed recursively. Out of the two, the following was shown to have better performance:

$$\hat{\mu}_m = \frac{1}{t_m} \sum_{j=1}^m s_j \bar{Y}_{\cdot,j} = \hat{\mu}_{m-1} + \frac{s_m}{t_m} \left( \bar{Y}_{\cdot,m} - \hat{\mu}_{m-1} \right), \tag{1}$$

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$$\hat{\sigma}_{1,m}^2 = \frac{1}{t_m} \sum_{j=1}^m s_j \tau_j^2 = \hat{\sigma}_{1,m-1}^2 + \frac{s_m}{t_m} \left( \tau_m^2 - \hat{\sigma}_{1,m-1}^2 \right).$$
<sup>(2)</sup>

Based on the above, *a* and *b* at the *m*th stage can be estimated by  $\hat{a}_{1,m} = \hat{\mu}_m^2 / \hat{\sigma}_{1,m}^2$  and  $\hat{b}_{1,m} = \hat{\mu}_m / \hat{\sigma}_{1,m}^2$ , respectively. Notice that  $t_m = \sum_{j=1}^m s_j$ , we have  $E(\hat{\mu}_m) = \frac{1}{t_m} \sum_{j=1}^m s_j E(\bar{Y}_{.j}) = \mu$  and  $E(\hat{\sigma}_{1,m}^2) = \frac{1}{t_m} \sum_{j=1}^m s_j E(\tau_j^2) = \sigma^2$ . Besides,  $\hat{\mu}_m$  and  $\hat{\sigma}_{1,m}^2$  are linear combination of  $\{\bar{Y}_{.j}, j = 1, \dots, m\}$  and  $\{\hat{\sigma}_{1,m}^2, j = 1, \dots, m\}$ , respectively. Thus, both  $\hat{\mu}_m$  and  $\hat{\sigma}_{1,m}^2$  are linear unbiased estimators. Linear unbiased estimator has been widely used in statistics. The merit of linear unbiased 10 11 estimator is that it can be constructed easily and be derived recursively. For example, least squares estimator for the linear 12 regression model is a linear combination of the observations, and is also the best linear unbiased estimator (BLUE) of the 13 model parameters. The basic idea to select the BLUE is to find the estimator with the smallest variance in a set of linear unbiased estimators. In view of the fact that Paroissin (2017)'s estimators are linear unbiased estimators, the objective of this paper is to improve these estimators by finding the BLUEs of  $\mu$  and  $\sigma^2$ .

The paper is organized as follows. In Section 2, we propose two new estimators, and the consistency of the estimators is shown. In Section 3, a simulation study is performed to compare the new estimators with these from Paroissin (2017). A 18 data set is analyzed for illustration in Section 4. Finally, we give a conclusion of this paper. 19

#### 2. New estimators 20

As mentioned before, both estimators proposed by Paroissin (2017) are linear unbiased estimators. This observation 21 motivates us to find more efficient estimators in the set of linear unbiased estimators of  $\mu$  and  $\sigma^2$ . For the parameter  $\mu$ , we consider the set of linear unbiased estimators  $U_{\mu} = \{\sum_{j=1}^{m} \alpha_j \bar{Y}_{.j}, \sum_{j=1}^{m} \alpha_j = 1\}$ . Then, for any  $\hat{\mu} \in U_{\mu}$ , 22 23

Var
$$(\hat{\mu}) = \sum_{j=1}^{m} \alpha_j^2 \operatorname{Var}\left(\bar{Y}_{.j}\right) = \sum_{j=1}^{m} \alpha_j^2 \sigma^2 / (ns_j).$$

Taking the first derivatives of Var( $\hat{\mu}$ ) with respect to  $\alpha_i$ , and letting them equal zero, we have 25

$$\alpha_j/(ns_j) - (1 - \alpha_1 - \dots - \alpha_{m-1})/(ns_m) = 0, \ j = 1, 2, \dots, m-1$$

which leads to  $\alpha_j = s_j/(s_1 + s_2 + \cdots + s_m) = s_j/t_m$ . Thus,  $\hat{\mu}_m \ln(1)$  is the best linear unbiased estimator in the set  $U_{\mu}$ . Similarly, 27 for the parameter  $\sigma^2$ , we consider the set of linear unbiased estimators  $U_{\sigma^2} = \{\sum_{i=1}^m \beta_j \tau_i^2, \sum_{i=1}^m \beta_j = 1\}$ . From Paroissin 28 (2017), we have 29

<sup>30</sup> 
$$\operatorname{Var}(\tau_j^2) = \frac{2a^2}{(n-1)b^4} + \frac{6a}{nb^4s_j} = V_1(1+V_0/s_j),$$

where  $V_1 = \frac{2a^2}{(n-1)b^4}$  and  $V_0 = \frac{3(n-1)}{na}$ . For any  $\hat{\sigma}^2 \in U_{\sigma^2}$ , 31

$$\operatorname{Var}(\hat{\sigma}^2) = \sum_{j=1}^m \beta_j^2 \operatorname{Var}\left(\tau_j^2\right) = \sum_{j=1}^m \beta_j^2 V_1(1 + V_0/s_j).$$

Taking the first derivatives of Var $(\hat{\sigma}^2)$  with respect to  $\beta_i$ , and letting them equal zero, we have 33

$$\beta_j(1+V_0/s_j)-(1-\beta_1-\cdots-\beta_{m-1})(1+V_0/s_m)=0, \ j=1,2,\ldots,m-1,$$

which follows that 35

$$\beta_j = \frac{(1+V_0/s_j)^{-1}}{\sum_{j=1}^m (1+V_0/s_j)^{-1}}.$$
(3)

Thus, if the shape parameter a is known, then the best linear unbiased estimator in the set  $U_{\sigma^2}$  is 37

$$\hat{\sigma}_m^2 = \frac{\sum_{j=1}^m (1+V_0/s_j)^{-1} \tau_j^2}{\sum_{j=1}^m (1+V_0/s_j)^{-1}} = \hat{\sigma}_{m-1}^2 + \frac{(1+V_0/s_m)^{-1} (\tau_m^2 - \hat{\sigma}_{m-1}^2)}{\sum_{j=1}^m (1+V_0/s_j)^{-1}}.$$

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